

MECHANICAL DESIGN OF MIRAS INFRARED MICROSCOPY BEAM LINE AT ALBA

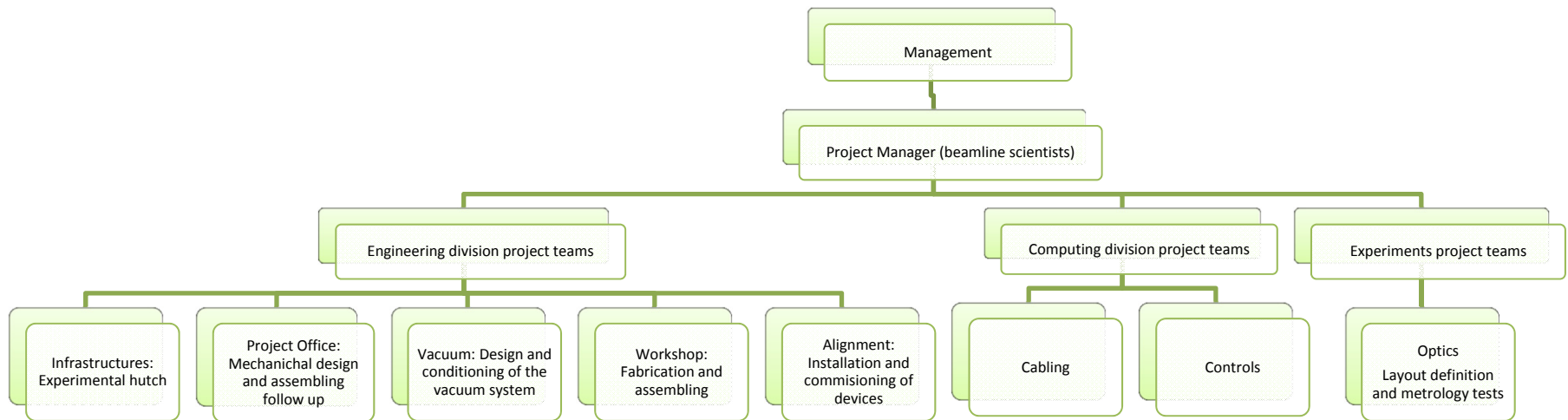
ALBA Synchrotron Light Source, Engineering division, Transversal section

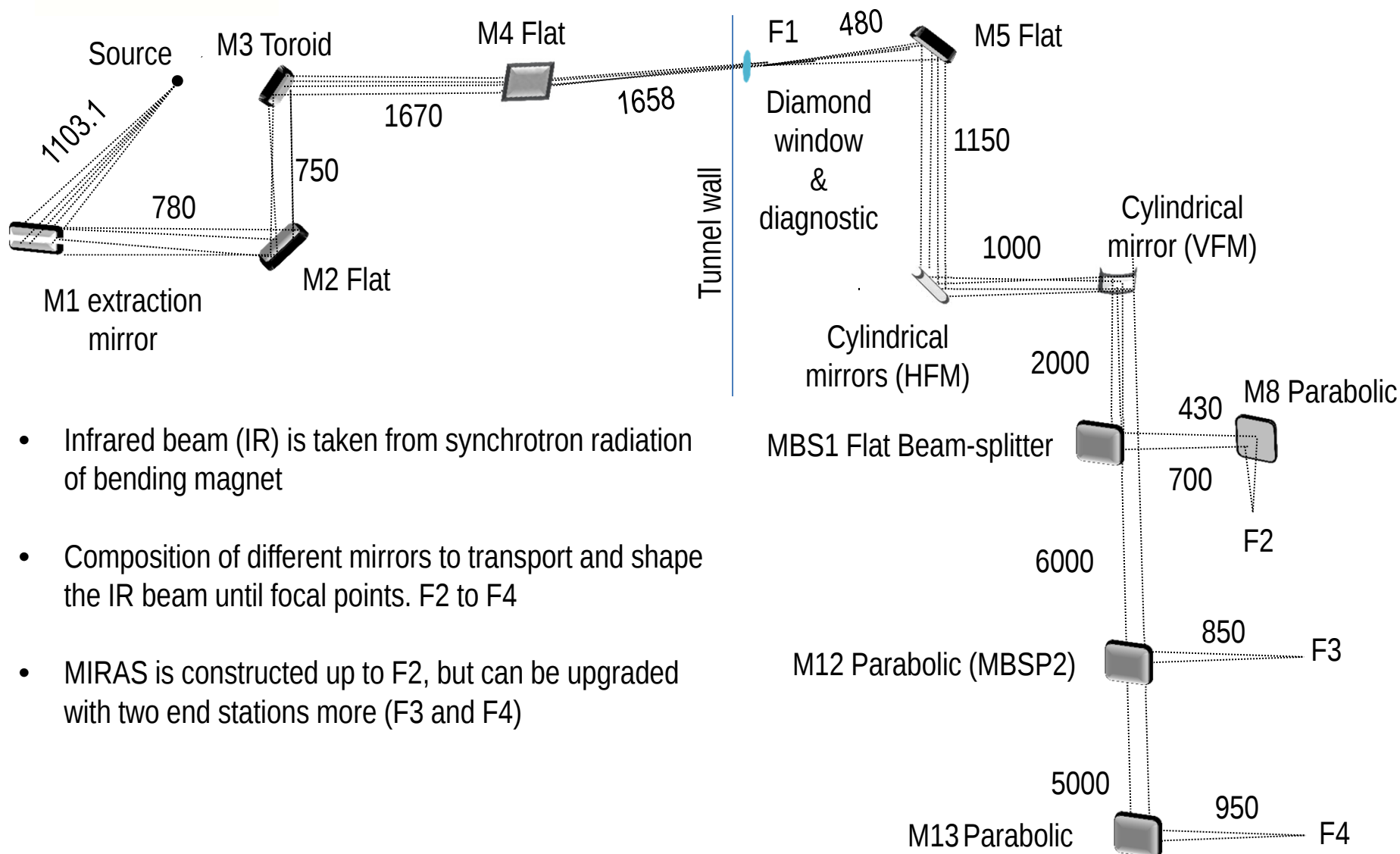
Llibert Ribó, Igors Sics, Josep Nicolas Artur Gevoryan, Alejandro Crisol, Carles Colldelram, Liudmila Nikitina, Raquel Monge, Marcos Quispe



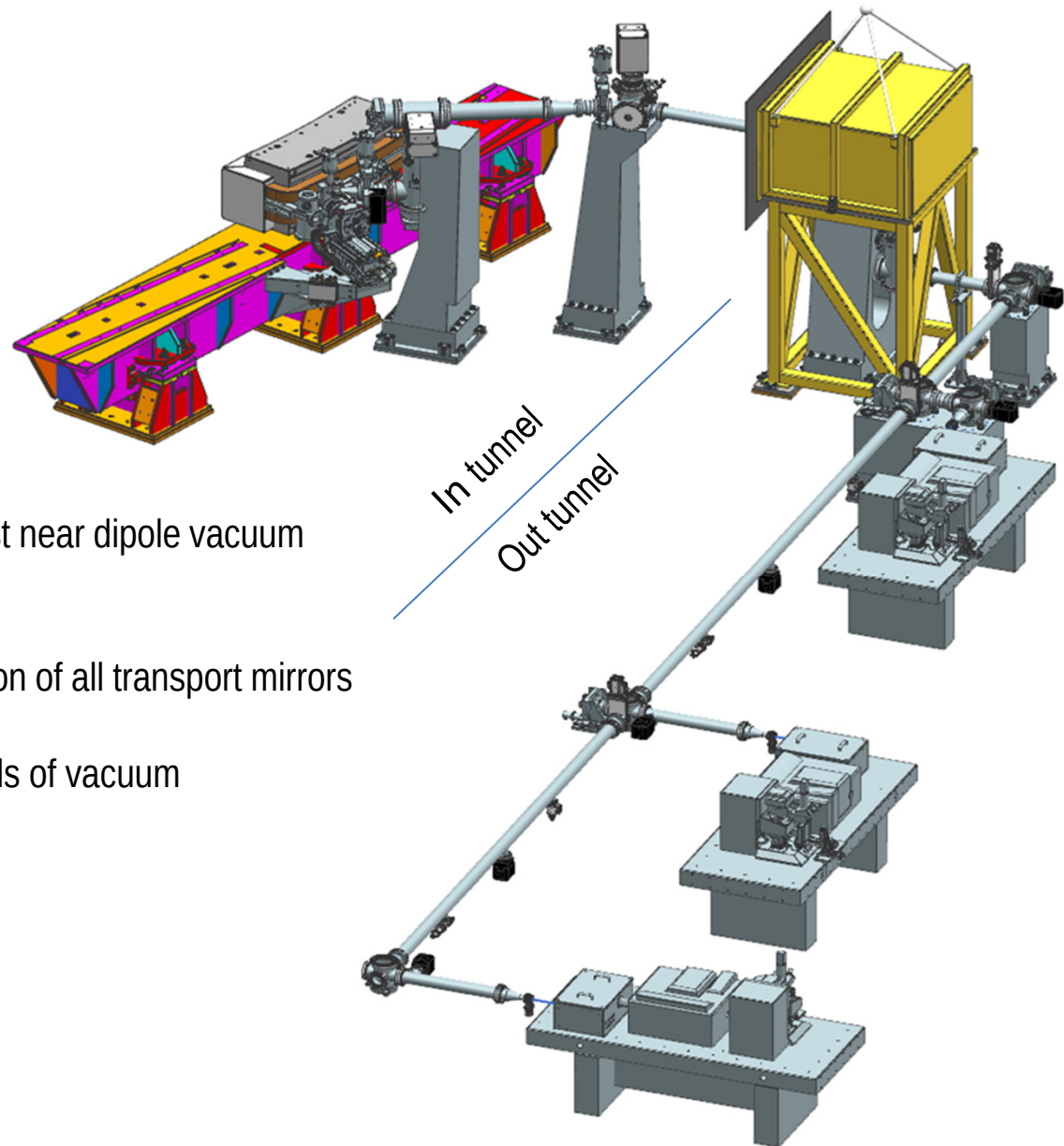
- ***Schedule***
- ***Layout / Overall view***
- ***Extraction Mirror M1***
- ***Transport mirrors***
- ***Front end inside tunnel***
- ***Beamline outside tunnel***
- ***Installation***
- ***Commissioning***

- Project starts on 2013 First design and first layout definition 2014. Strong collaboration and advice from Soleil
- First beam observed early 2016
- First friendly users Spring 2016. First official user October 2016
- Taken by ALBA as an in house project. Different teams from all divisions are asked to provide different work packages





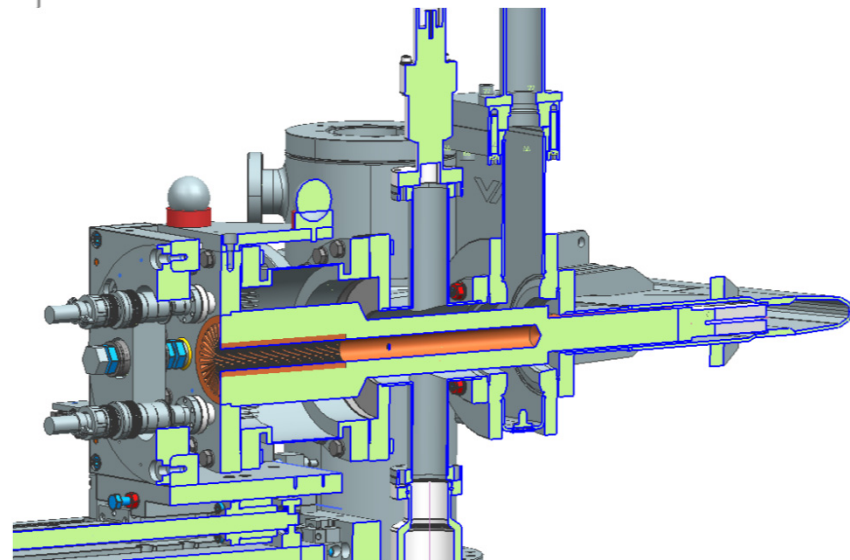
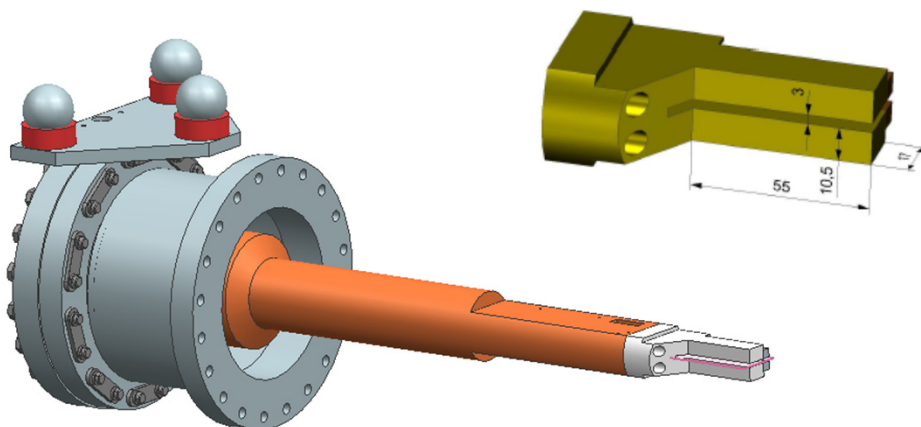
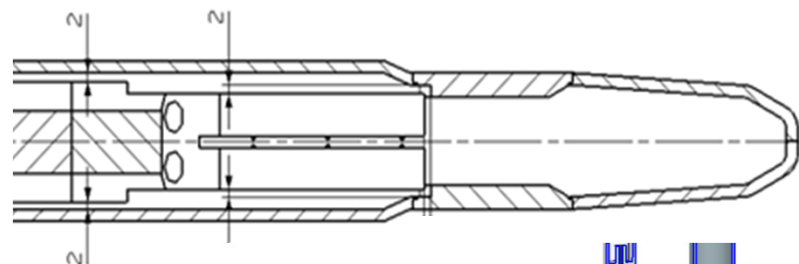
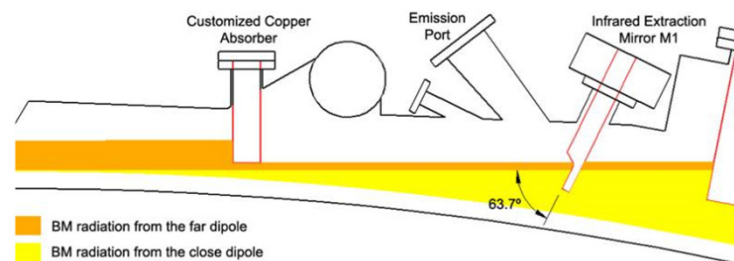
- Infrared beam (IR) is taken from synchrotron radiation of bending magnet
- Composition of different mirrors to transport and shape the IR beam until focal points. F2 to F4
- MIRAS is constructed up to F2, but can be upgraded with two end stations more (F3 and F4)



- Extraction mirror mechanism just near dipole vacuum chamber
- Mechanisms to adjust the position of all transport mirrors
- Vacuum system. 2 different levels of vacuum
- Supports and pedestals
- Small lead hutch
- End stations

Extraction Mirror M1.

- M1 takes IR from far and close Bending magnets,
- U shaped 2 parts separated by a 3 mm slot
- Optimized optical surface, very tight clearances with the dipole chamber (2 mm)
- UHV compatible Thermocouples array to adjust the mirror height in respect to the orbit plane
- 2 thermocouples to measure temperature body
- Cooper Arm to position the mirror inside dipole chamber heat dissipation with no use of water cooling.
- Temperature at mirror body expected at 400 mA of 63°C (see M.Quispe contribution TUPE11)



M1 positioner design.

Insertion / extraction:

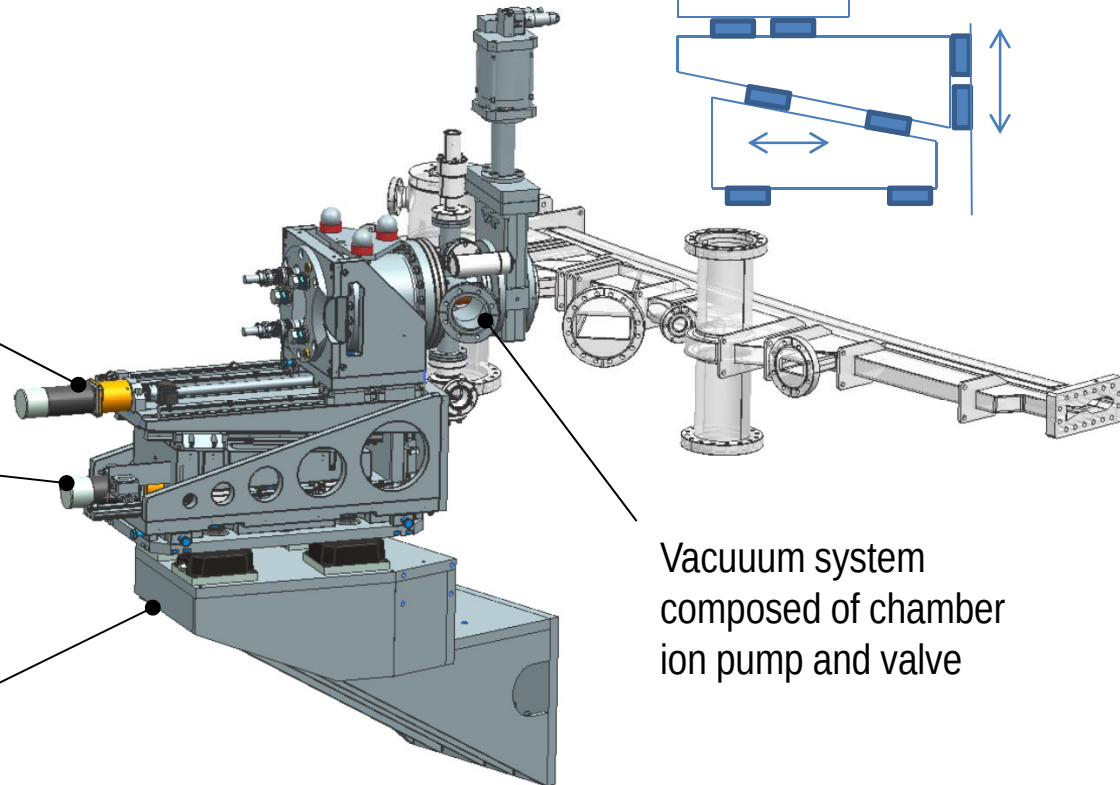
- Motorized horizontal long spindle
- Cooper arm guided
- Range 300 mm

Vertical movement: M1 positioning

- Based on wedgemount system
- Very short range ± 1 mm

Both movements are encoded to record the position

All attached to guirder by steel interface



M1 positioner design.

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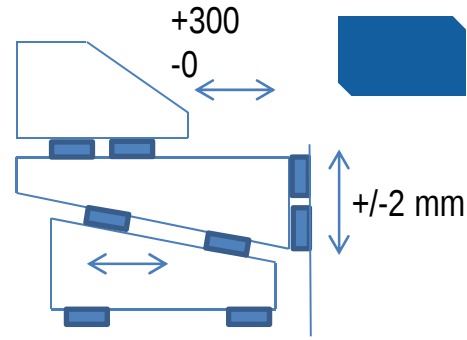
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Vertical movement: M1 positioning

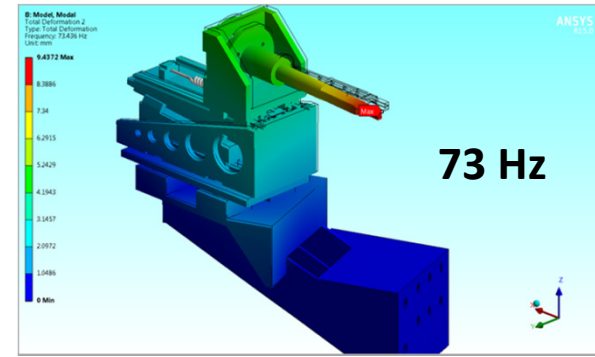
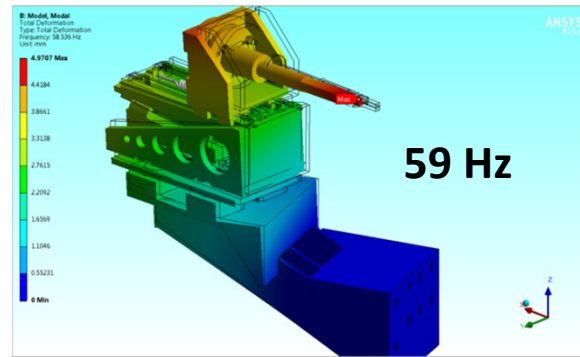
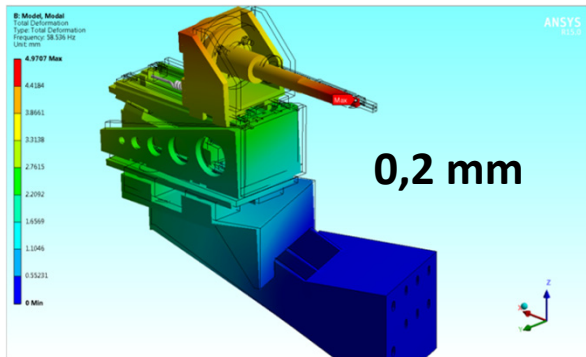
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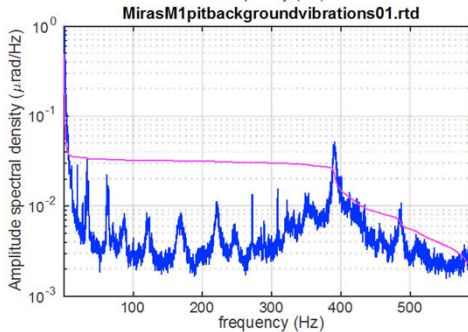
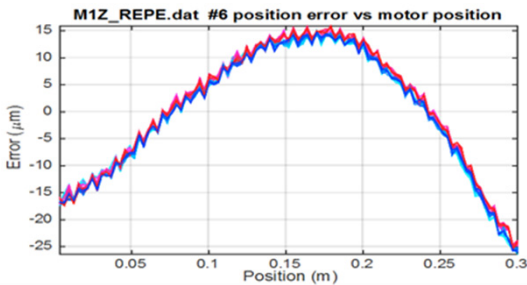
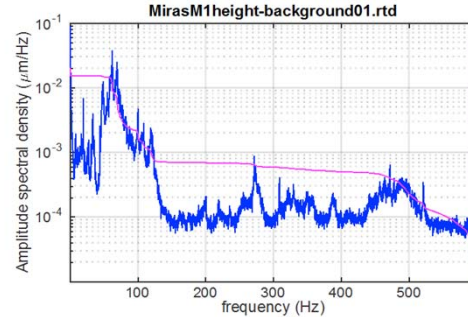
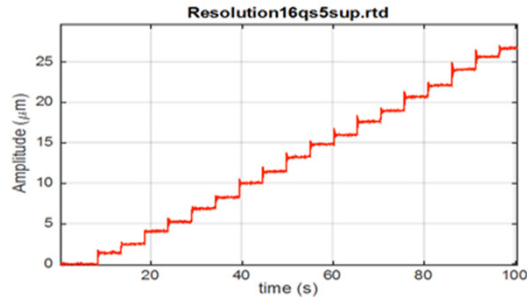
All attached to guider by steel interface



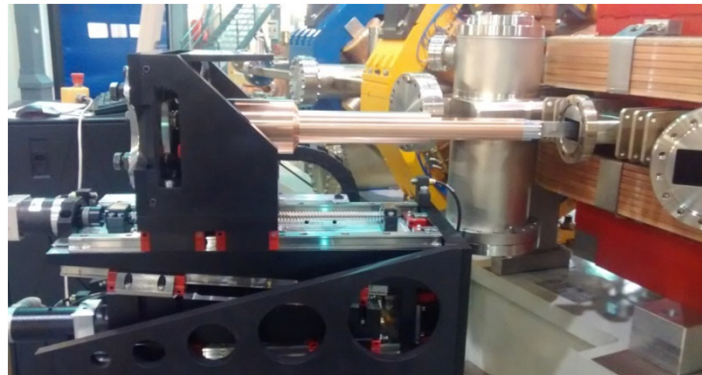
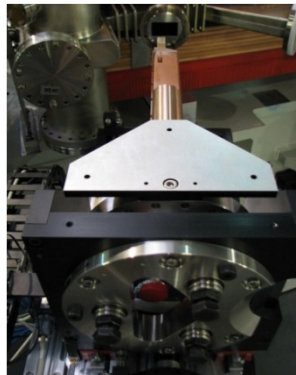
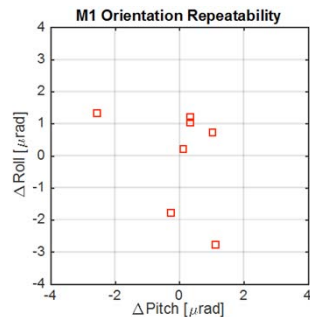
Vacuum system composed of chamber ion pump and valve



M1 positioner performance.



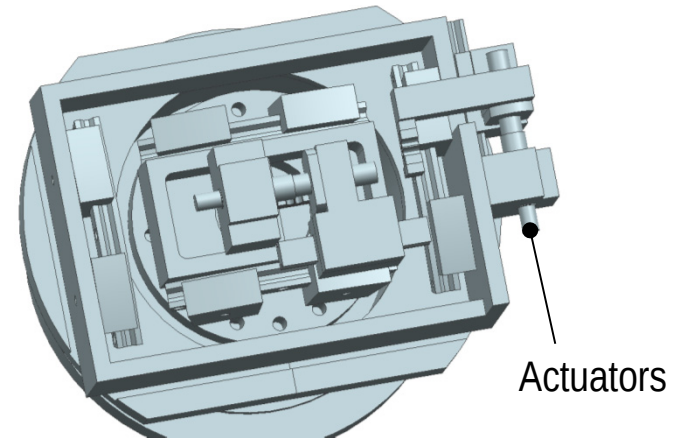
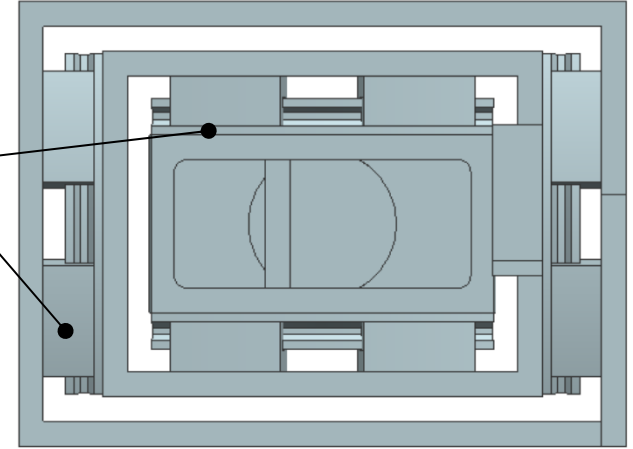
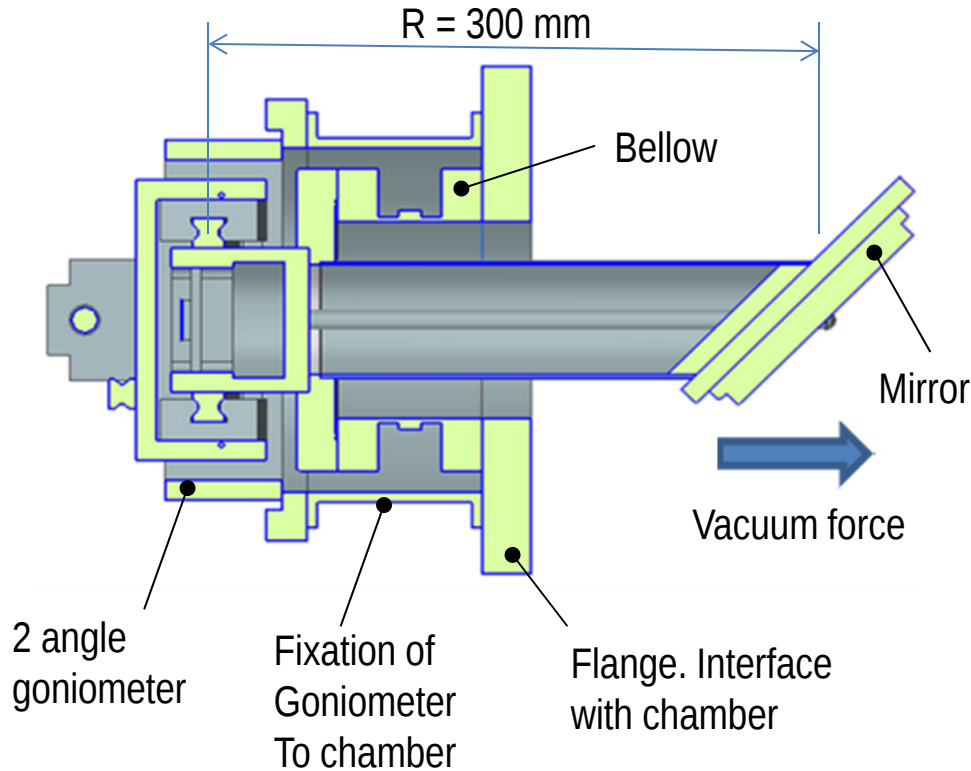
- Resolution of longitudinal movement spot after 4 full steps → 1,6 μm/ 4 steps
- Deviation 15 μm in respect to actuator theoretical position
- Repeatability 1,1 μm
- M1 Orientation repeatability after in / out between 3 and 4 μrad
- Height background: 27 nm at 61 Hz
- Pitch background 400 Hz



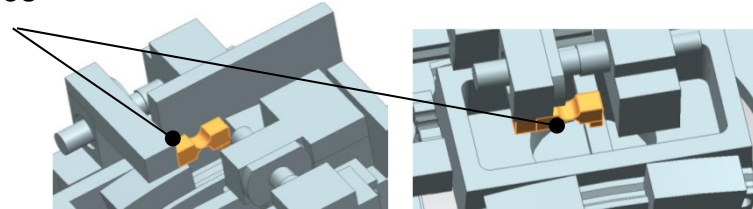
Transport mirror mechanism.

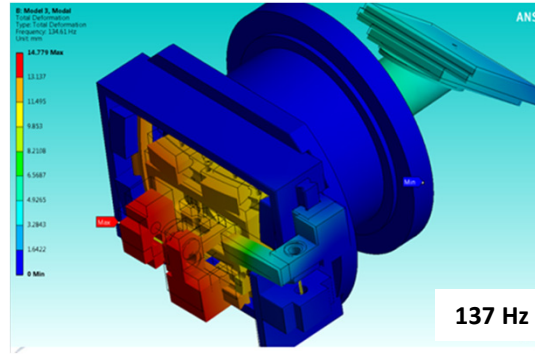
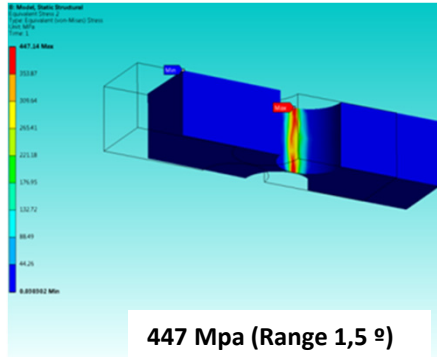
Range	$\pm 9.07 \text{ mrad}$	$\pm 1^\circ$
Resolution	$15 \mu\text{rad}$	$9 \cdot 10^{-4}^\circ$
Accuracy	0.25 mrad	0.014°
Repeatability	$32 \mu\text{rad}$	$2 \cdot 10^{-4}^\circ$

Circular guides
300 mm radius



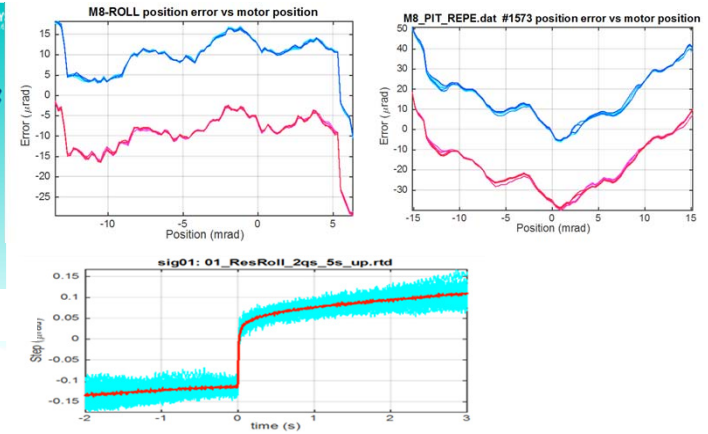
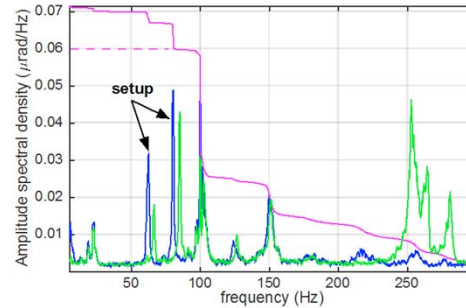
flexures



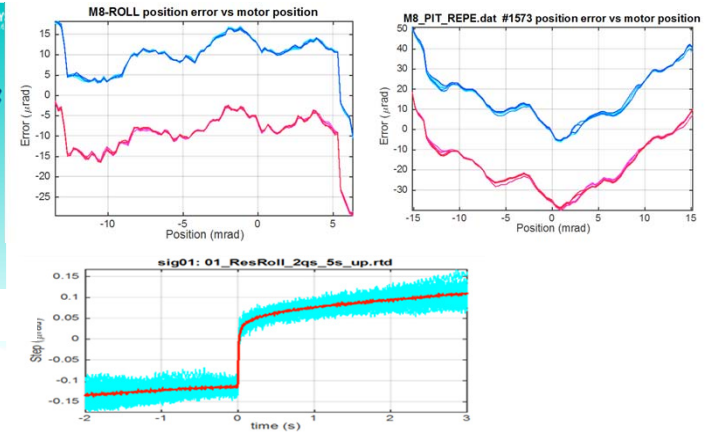
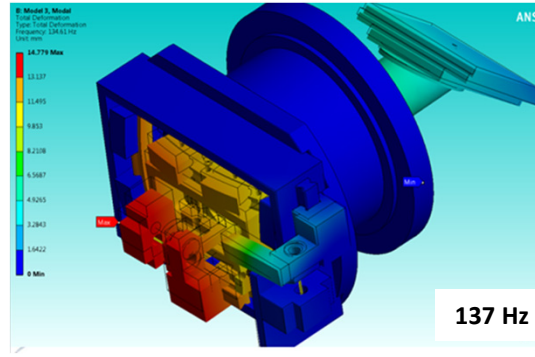
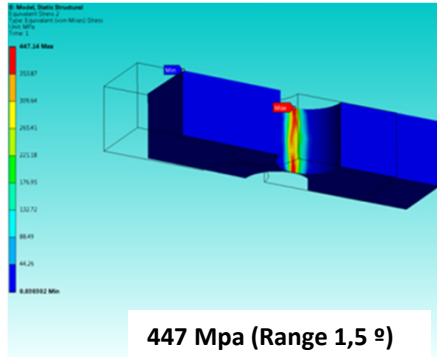


TEST	UNE-EN ISO 6892
L.Elastico/Y.Strenht	Resistencia/Tensite
ReH	R _m
MPa	MPa
820	1001
825	1018

ure = RT (RT = Temperatura Ambiel)

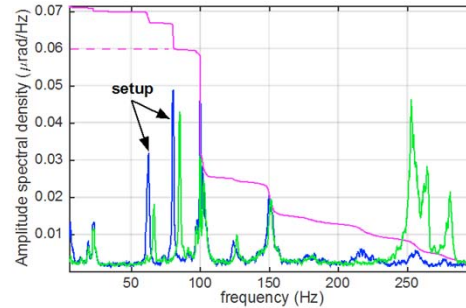


- 0.16 μrad /half step
- Accuracy open loop 57,2 μrad
- Peak resonance 98 Hz amplitude 0,06 μrad

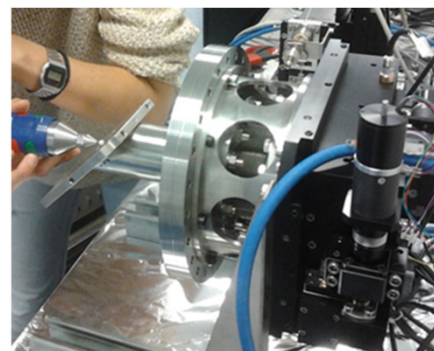
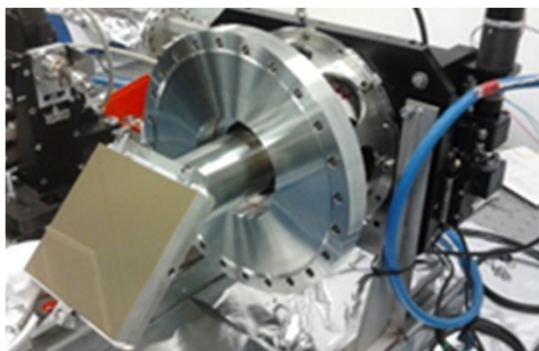


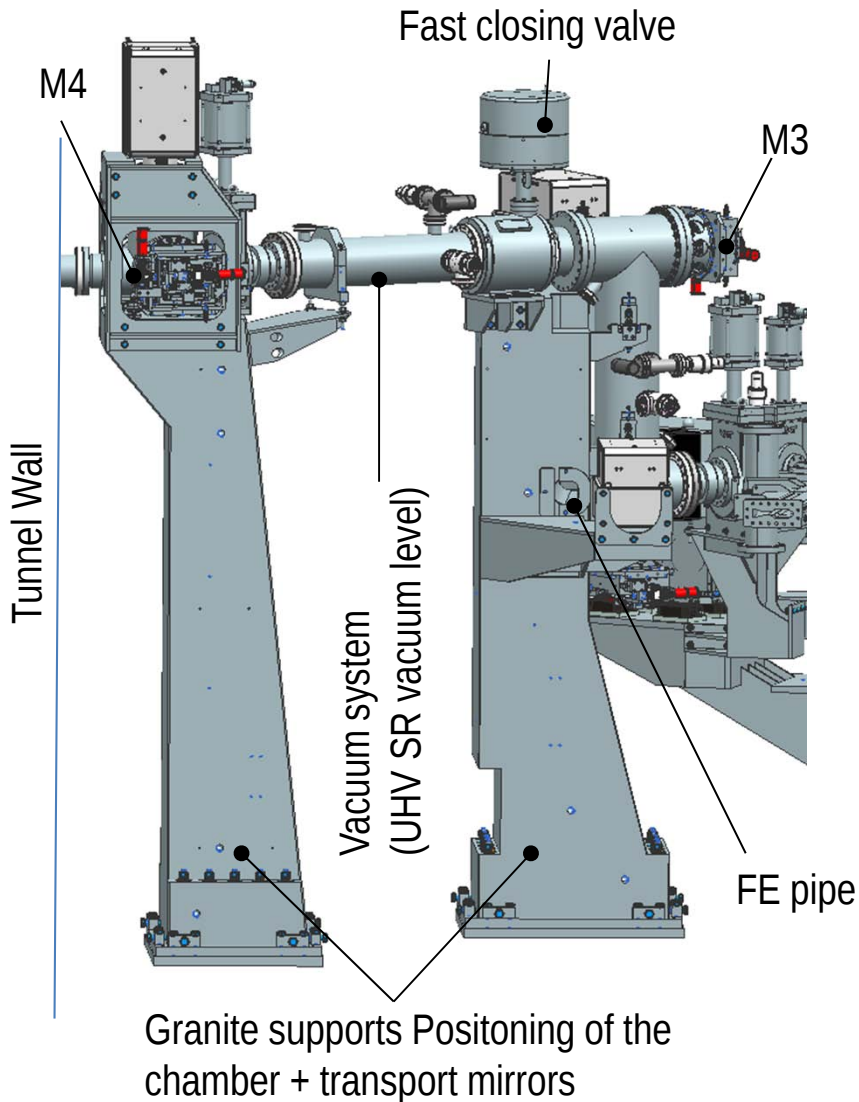
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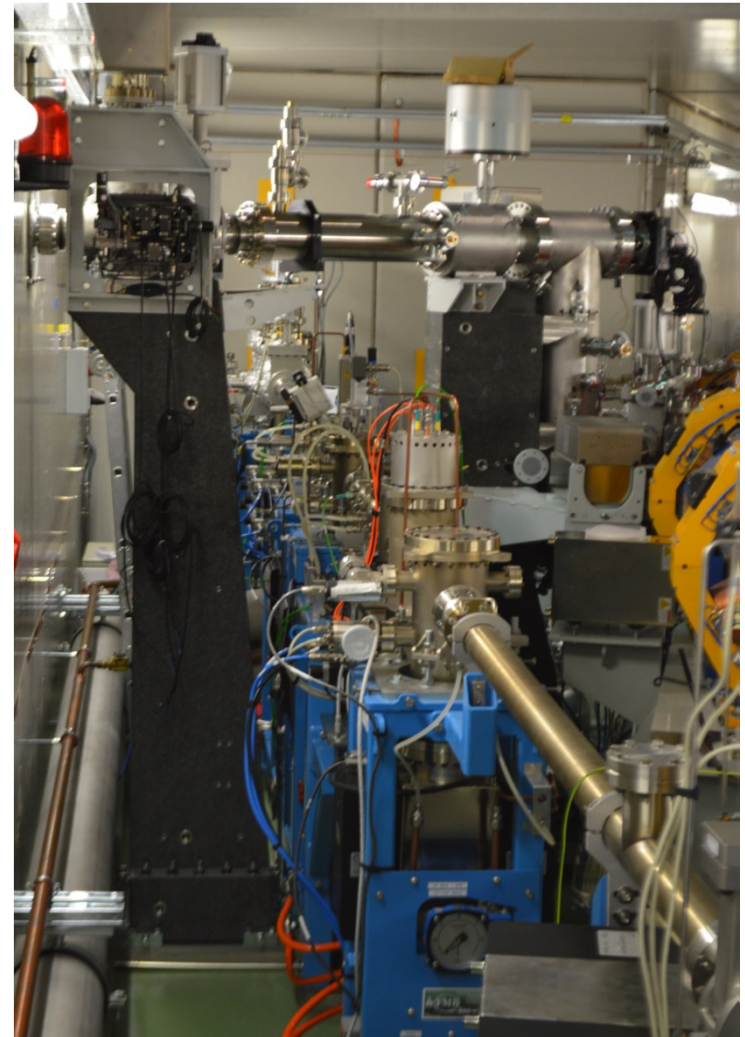
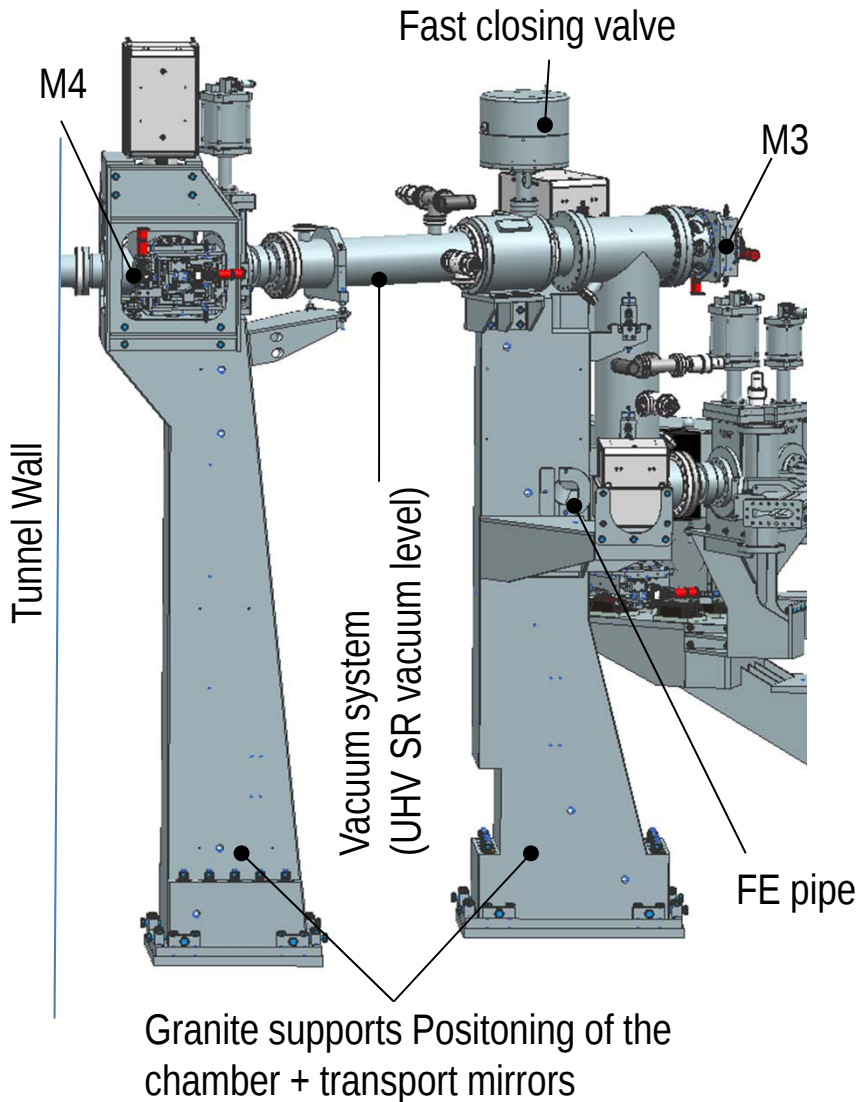


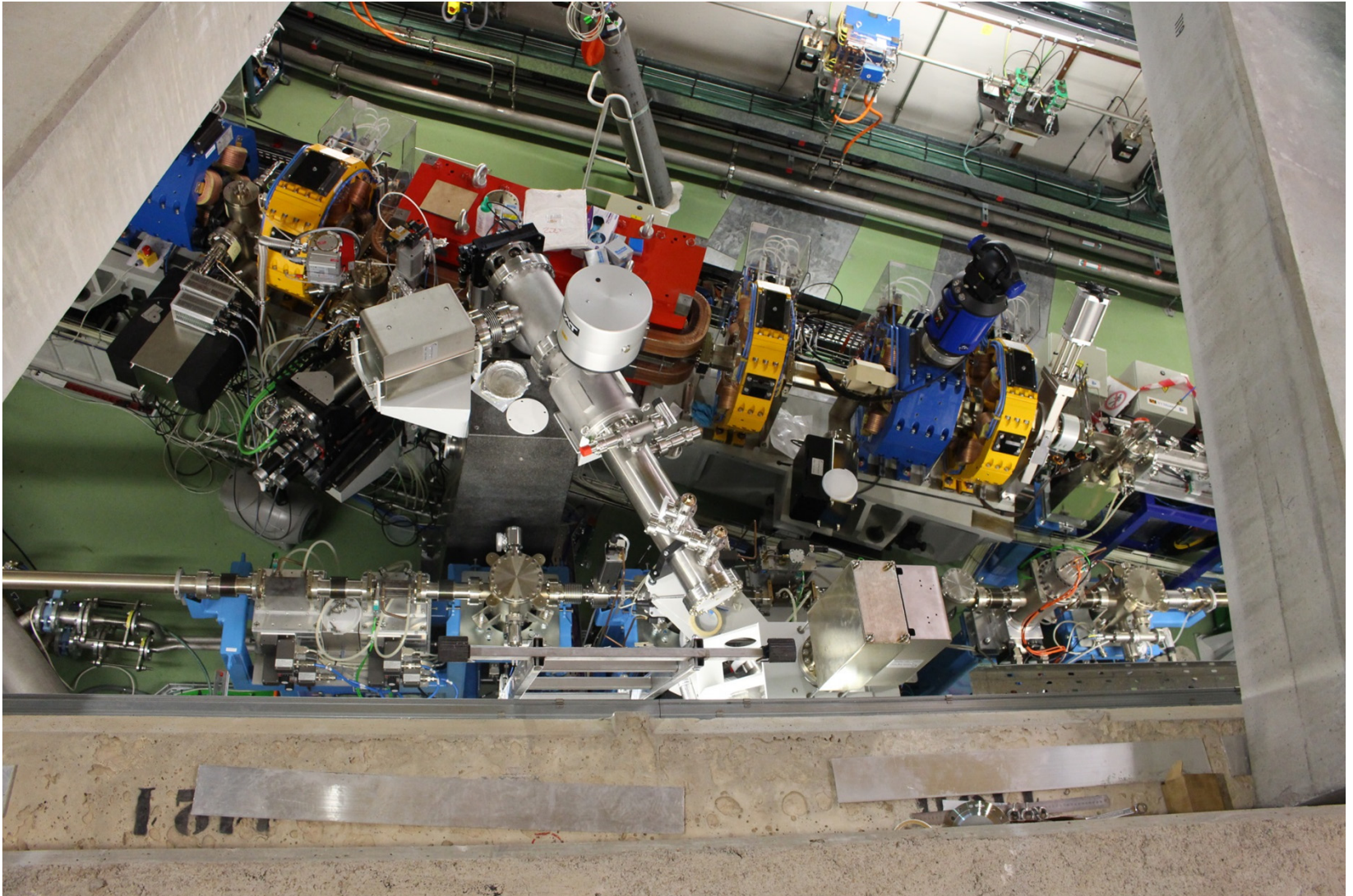
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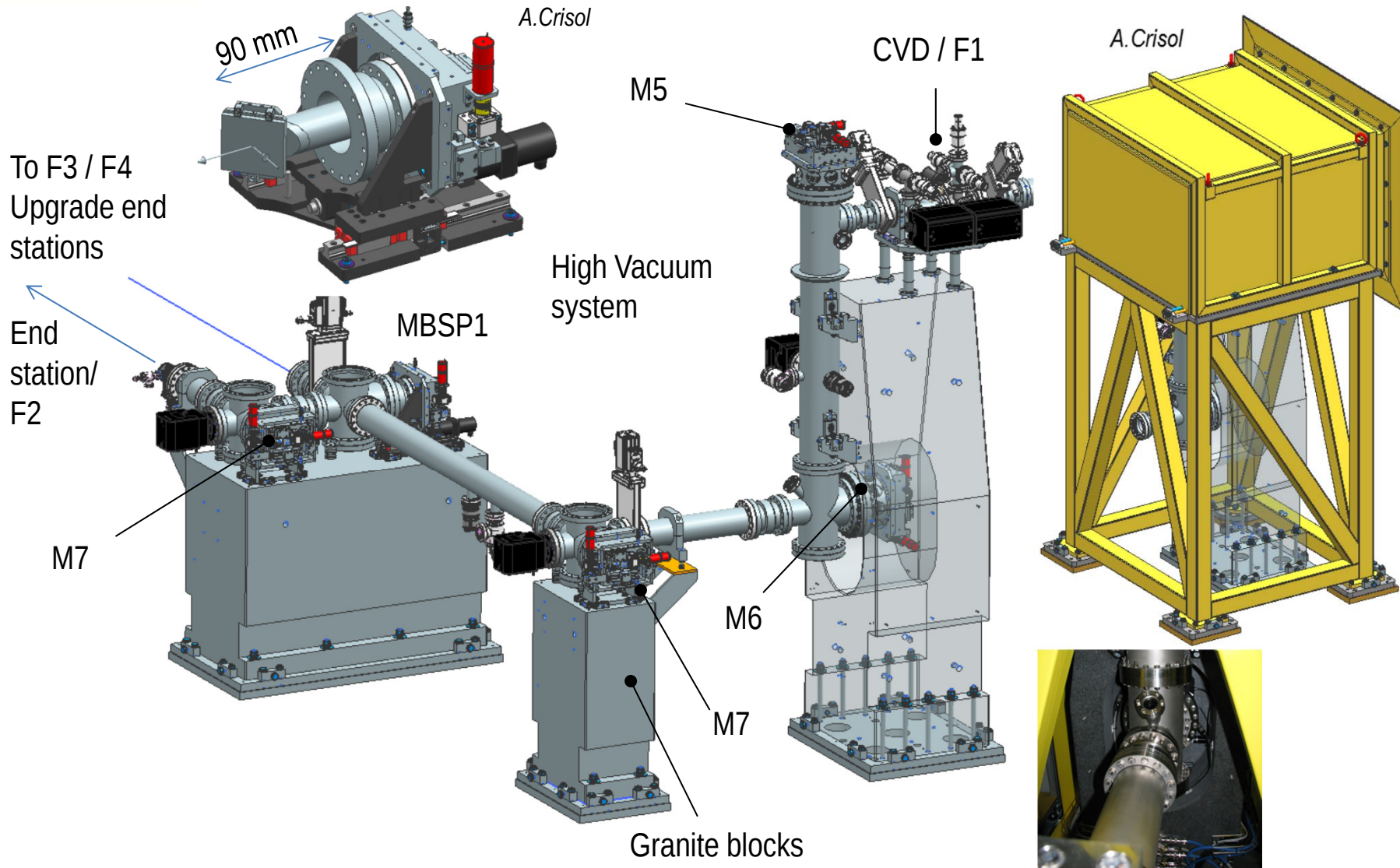


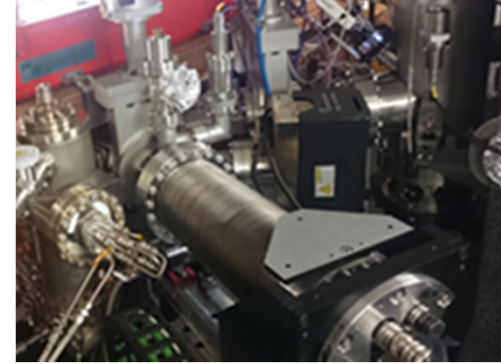
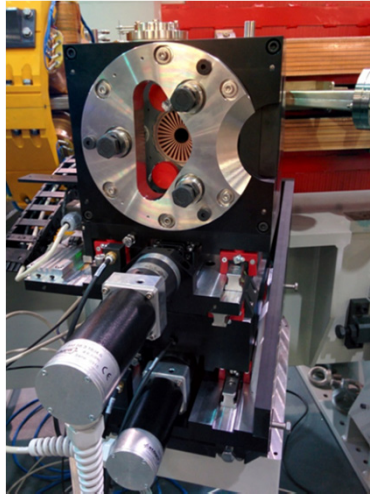
Front end Inside Tunnel

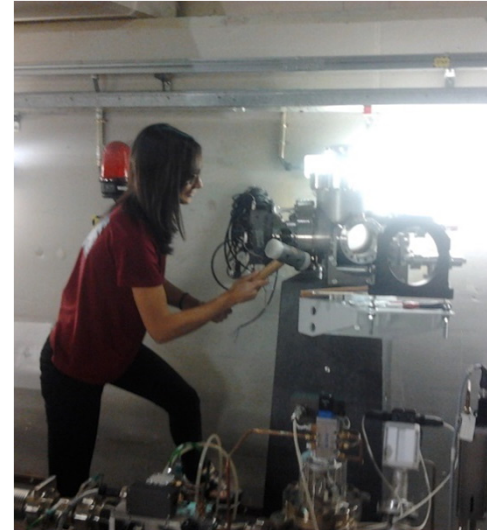
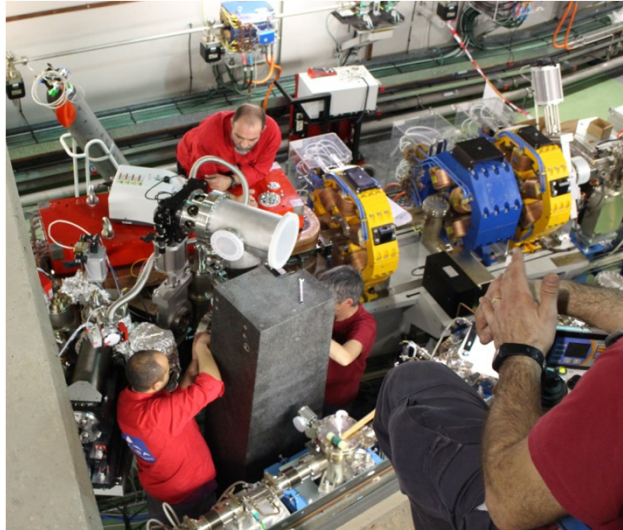
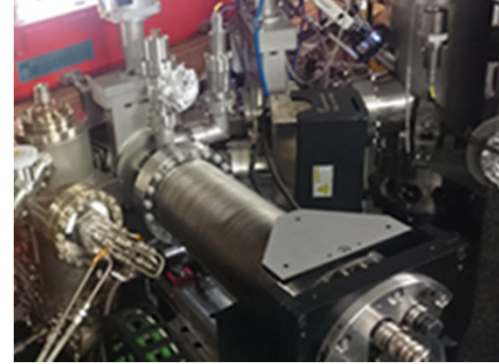
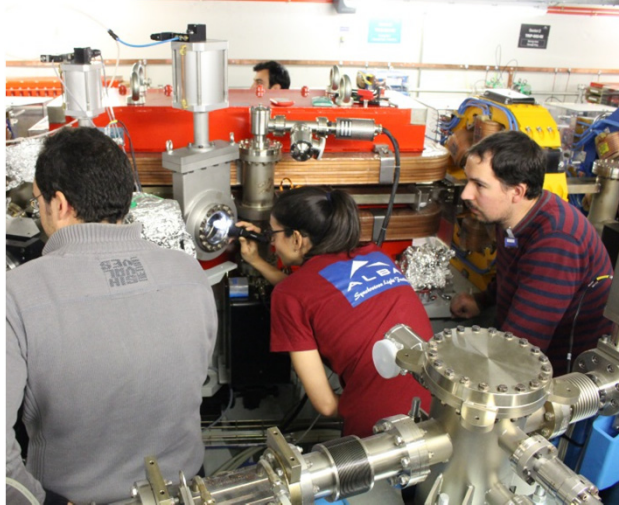
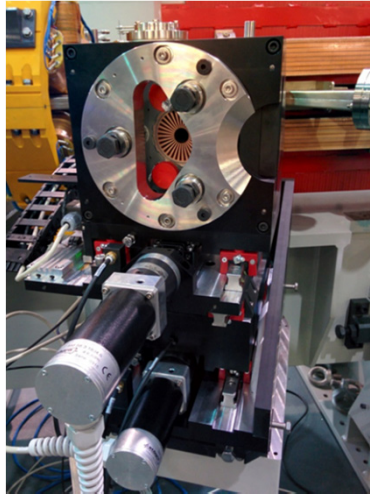


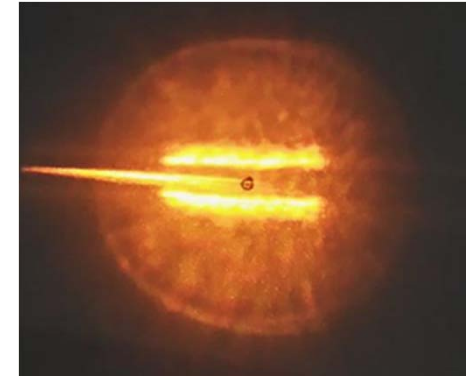
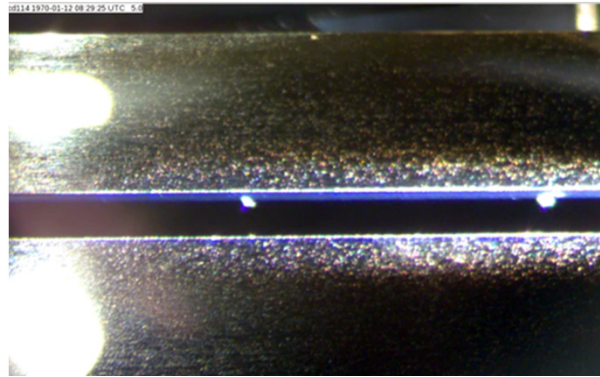
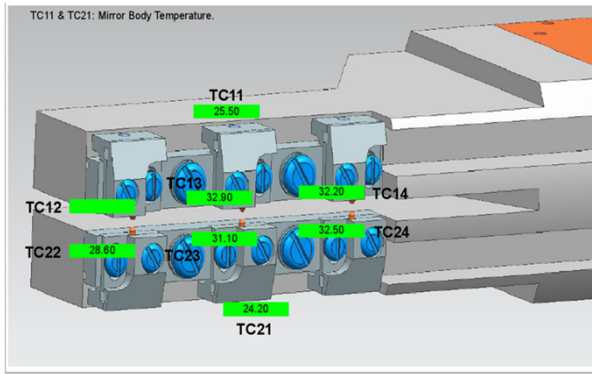


Beamline outside tunnel





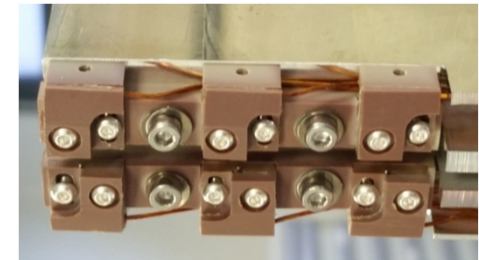




- Beam current 130 mA
- Temperatures on M1 slot between 28°C and 32,5°C
- Temperature mirror body 25,5°C → simulations OK (See M. Quispe Report TUPE11)

Next steps

- First installed type K thermocouples were affected by synchrotron radiation generating a pressure increase in S02
- There were replaced by other type of thermocouples UHV compatible and radiation resistive → provisional solution
- PEEK supports seems to be degraded due to the radiation
- Definitive solution → thermocouples covered by stainless steel and ALUMINA supports





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Paul Dumas and Gary Ellis
Domingo Alloza
Igors Sics*

Thanks to all of you for your attention

